PRELIMINARY

LOG SHEETS AND PROTOTYPE REFERENCE CARTRIDGES MUST BE RETURNED TO COLORADO UPON REQUEST FROM CSSE

RLØ1 RLØ2 ALIGNMENT CARTRIDGE PROCEDURE

Version (Preliminary)

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RLØ1 RLØ2 ALIGNMENT CARTRIDGE PROCEDURE

Version (Preliminary)

PRELIMINARY

NOTE: Perform inspection and cleaning of heads, spindle, spindle cone and disk well, prior to performing this procedure.

1.0 READ SIGNAL AMPLITUDE CHECK and/or ALIGNMENT

1.1 REQUIRED TOOLS

- Calibrated Oscilloscope with 2 probes
- 2. One DIP clip, one pin-to-pin jumper, & one test lead (aligator clip)

OR

- Two (2) DIP clips and two (2) pin-to-pin jumpers.
- 3. Diagnostic listed in Appendix A or toggle-in programs listed in Appendix B & C. (for head selection)
- 4. Standard Reference Cartridge (RLØ1K-RF or RLØ2K-RF)

1.2 EQUIPMENT SETUP

OSCILLOSCOPE

Channel 1 Probe - Servo Data, R/W Module TP2
Channel 1 Ground - Signal Gnd, R/W Module TP3

Coupling - DC

Vertical Mode - Channel 1

Vertical Gain - (Outer Cyl) 500mv/div (50mv/div. w/Xl0 probe) - (Inner Cyl) 200mv/div (20mv/div. w/Xl0 probe)

Ext. Sync Probe - DLM version 1 , TP9 (sector time) - DLM version 2 , TP11 (sector time) - DLM version 3 , TP11 (sector time)

Ext. Sync Gnd - DLM (all) , TP2 (signal gnd)

Trigger Source - External

Trigger Coupling - AC

Trigger Slope - Negative

Sweep time - 5us/div.

Sweep mode - Auto or Norm. trigger

1.3 PROCEDURE - Amplitude Check/Adjust

- Remove both top cover assemblies from the RL Drive.
- 2. Defeat SK TO (Seek Timeout) & Cover Interlock (Appendix D).
- 3. Place R/W module assembly up and out of the way to expose the carriage assembly.
- 4. Install Standard Reference Cartridge (RLO1K-RF or RLO2K-RF).
- 5. Press WRITE PROT switch to IN.
- 6. Press LOAD switch to IN and wait for the heads to load onto the cartridge.
- 7. Set the vertical gain to display a deflection of 500mv/div and observe the S1 Servo waveform similar to the one shown below.

S2

S1

Time = 5us/div.

Figure 1

- 8. Measure and record the peak-to-peak amplitude of the S1 burst for both heads on this cylinder (Cylinder 0).
- 9. CAREFULLY move the positioner towards the spindle to the innermost cylinder. Be sure to "CAREFULLY" grab the positioner and NOT the heads themselves. You will feel a slight "detented" resistance when moving the positioner. The resistance will become noticeably greater when you attempt to move beyond the innermost cylinder into the inner guardband. Merely release the positioner and allow it to lock onto the inner cylinder.

1.3 PROCEDURE - Amplitude Check/Adjust (continued)

- 10. Set the vertical gain to display a deflection of 200mv/div and observe the Sl Servo waveform similar to the one shown in Fig 1.
- 11. Measure and record the peak-to-peak amplitude of the Sl burst for both heads on this cylinder (Cylinder 255 for RLØl or Cylinder 511 for RLØ2).
- 12. Adjust the read gain pot on the R/W module (see Appendix E) VALUE until one of the heads is EQUAL to its' REFERENCE AMPLITUDE ON SETTING and the other head is EQUAL to or GREATER THAN its' LAGE REFERENCE AMPLITUDE SETTING. Use care in loosening the glyptal CALTUI before adjusting the pot. Adjustments are to be made at the inner cylinder only. Do not make adjustments at the outer cylinder.

Note: NO HEAD SHOULD BE ADJUSTED TO A VALUE BELOW ITS' REFERENCE AMPLITUDE SETTING.

13. If, after the previous adjustment, either head reads more than 200mv ABOVE its' REFERENCE AMPLITUDE SETTING, then one or both heads must be replaced. Two (2) approaches may be used:

NOTE: The 200 mv limit applies to reading obtained at the inner cylinder only, outer cylinder readings are for information only.

13-1 Replace the head with the "lowest" amplitude reading and repeat Step 12. If this does not reduce the difference to less than 200mv, then replace the "other" head and repeat Steps 9 thru 12.

-- OR --

- 13-2 Replace the "upper" head (it's the most accessable) and repeat Step 12. If this does not reduce the difference to less than 200mv, then replace the "lower" head and repeat Steps 9 thru 12.
- 14. Repeat the entire "check" procedure and record all values as "after adjustment" values.

.O SECTOR-to-S1 TIME CHECK and/or ADJUSTMENT

- Radial Alignment using the STANDARD REFERENCE CARTRIDGE
- The positioner radial alignment checks and verifies the following condition:
 - o The servo bursts (read by the read/write heads) must occur during the correct time period relative to the sector pulse (detected by the sector transducer at the hub). Because the sector transducer is fixed, changing the head positioner location affects this timing relationship.
 - o The servo burst/sector timing relationship must be the same at cylinder 0 and the innermost cylinder to assure the head carriage moves straight towards the the center of the cartridge.

2.1 REQUIRED TOOLS

- 1. Calibrated Oscilloscope with 2 probes
- - Two (2) DIP clips and two (2) pin-to-pin jumpers.
- Diagnostic listed in Appendix A or toggle-in programs listed in Appendix B & C. (for head selection)
- 4. Standard Reference Cartridge (RLO1K-RF or RLO2K-RF)

2.2 EQUIPMENT SETUP

OSCILLOSCOPE

Channel 1 Probe - Servo Data, R/W Module TP2
Channel 1 Ground - Signal Gnd, R/W Module TP3
Coupling - DC
Vertical Mode - Channel 1
Vertical Gain - (Outer Cyl) 500mv/div (50mv/div. w/X10 probe)
- (Inner Cyl) 200mv/div (20mv/div. w/X10 probe)

Ext. Sync Probe

- DLM version 1 , TP9 (sector time)
- DLM version 2 , TP11 (sector time)
- DLM version 3 , TP11 (sector time)
Ext. Sync Gnd
- DLM (all) , TP2 (signal gnd)

Trigger Source - External
Trigger Coupling - AC
Trigger Slope - Negative

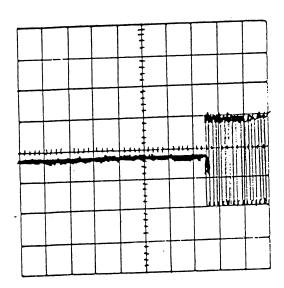
Sweep time - 2us/div.

Sweep mode - Auto or Norm. trigger

.

2.3 PROCEDURE - Sector-to-S1 Check

- v1. Remove both top cover assemblies from the RL Drive.
- 2. Defeat SK TO (Seek Timeout) and Cover Interlock. (Appendix D)
- 3. Place the read/write module assembly up and away to expose the carriage assembly.
- 4. Install the STANDARD REFERENCE CARTRIDGE.
- 5. Press WRT PROT switch to IN.
- 6. Depress LOAD switch to IN and wait for the heads to load onto the cartridge.
- 7. Select head 0. (Appendix A)
- 8. Set the vertical gain to display a deflection of 500mv/div on the oscilloscope and observe a waveform similar to the one shown below.



Time = 2us/div.

Figure 2

9. Measure the time between the start of the trace and the beginning of the S1 servo burst when the positioner is on Cylinder O. Record this value.

*** See Note 2, Section 2.5 ***

2.3 PROCEDURE - Sector-to-S1 Check (continued)

- 10. Select Head 1. (Appendix A)
- 11. Repeat step 9 above for head 1 and record this value.
- 12. CAREFULLY move the positioner towards the spindle to the innermost cylinder. Be sure to "CAREFULLY" grab the positioner and NOT the heads themselves. You will feel a slight "detented" resistance when moving the positioner. The resistance will become noticeably greater when you attempt to move beyond the innermost cylinder into the inner guardband. Merely release the positioner and allow it to lock onto the inner cylinder.
- 13. Set the vertical gain to display a deflection of 200mv/div on the oscilloscope and observe a waveform similar to the one shown in Figure 2.
- 14. Measure the time between the start of the trace and the beginning of the S1 servo burst when the positioner is on this cylinder (255 for RLO1 or 511 for RLO2). Record this value for Head 1. (Note: Head 1 should still have been selected since step 10 above.)

*** See Note 2, Section 2.5 ***

- 15. Select Head 0.
- 16. Repeat step 14 above for head 0 and record this value.
- 17. COMPARE the Sector-to-S1 times written on the STANDARD REFERENCE CARTRIDGE for "HEAD 1" to the displayed values recorded in steps 9 and 11. Perform the alignment procedures in Section 2.4 if these values do not closely match.
- 18. If the alignment procedure was performed, repeat the check procedure and record all values as "after adjustment" values.
- 19. Review the "displayed" Sector-to-S1 times for "HEAD O" recorded in step 18 above.

2.3 PROCEDURE - Sector-to-S1 Check (continued)

- 20. ---- (Head 1 aligned Head 0 check) ----
 - o If the displayed value is greater than 17us or less than 13us at the "inner" or "outer" cylinder, replace head 0 and repeat the alignment procedure (section 2.4) and resord all new values per section 2.3.
 - o If Sector Jitter exists (Figure 4), then:
 - a) The "upper" limit for sector jitter must be 17us or less.
 - AND -
 - b) The "lower" limit for sector jitter must be 13us or greater.
 - o If these limits are exceeded, replace head 0 and repeat the Alignment procedure (section 2.4).
- 21. If the Head O limits in step 20 are still exceeded, try replacing Head 1 and repeat the Alignment procedure.

2.4 PROCEDURE - Sector-to-S1 Alignmment

- 1. Perform steps 1 thru 6 in Section 2.3.
- Select Head 1. (Appendix A)
- 3. Find the six (6) largest Phillips screws on the positioner baseplate shown in figure 3 below.

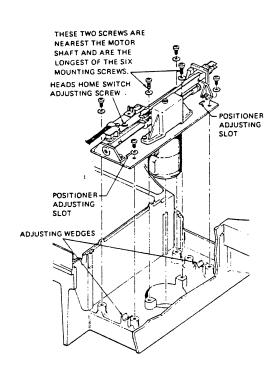


Figure 3

- 4. Slightly loosen but do not remove these 6 screws.
- 5. Insert two (2) flatblade screwdrivers into the positioner adjusting slots and adjust the positioner until the displayed servo time matches the S1 time recorded on the STANDARD REFERENCE CARTRIDGE for Surface 1. Track 0.
 - *** Refer to Notes 1 and 2, Section 2.5 ***
- 6. CAREFULLY move the positioner towards the spindle to the innermost cylinder. Be sure to "CAREFULLY" grab the positioner and NOT the heads themselves. You will feel a slight "detented" resistance when moving the positioner. The resistance will become noticeably greater when you attempt to move beyond the innermost cylinder into the inner guardband. Merely release the positioner and allow it to lock onto the inner cylinder.
- 7. Adjust the positioner until the displayed servo time matches the S1 time recorded on the STANDARD REFERENCE CARTRIDGE for Surface 1, Track 255 for RL01 or Track 511 for RL02.
- 8. Carefully tighten the 6 mounting screws in "small increments".
- 9. Perform the Alignment Check procedure in section 2.3.

?.5 SECTOR-to-S1 Alignment Notes

- Note 1. When aligning the positioner, adjust the "back" screwdriver when the heads are on an inner cylinder (255 or 511). Adjust the "front" screwdriver when the heads are on an outer cylinder (0).
- Note 2. When reading Sector-to-S1 time, some cartridges may exhibit "Sector Jitter". This is caused by slight variations of the distance between the machined sector slots on the cartridge hub. Figure 4 (below) shows an "Exaggerated" example of sector jitter when displayed on an oscilloscope.

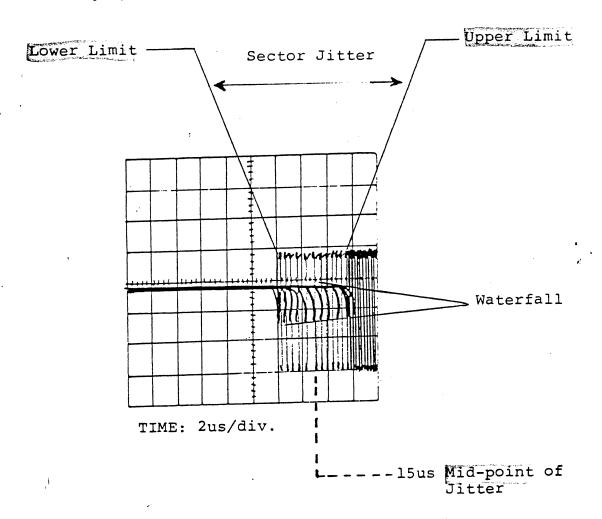


Fig. 4 S1 Servo Burst

Note the indicated "upper" and "lower" limits of the jitter. Also note the "waterfall" area caused by varying times of the S1 leading edge pulses for 40 sectors. Occassionally it may be easier to approximate the "range" of sector jitter by observing the "waterfall".

WHEN ADJUSTING OR MEASURING SECTOR-TO-S1 TIME AND DISPLAYABLE SECTOR JITTER EXISTS, THE "MIDPOINT" OF THE SECTOR JITTER RANGE SHOULD BE USED AS THE S1 TIME, NOT THE UPPER NOR LOWER LIMIT VALUES.

J.O HEAD ALIGNMENT CHECK and ADJUSTMENT

- o The heads should be checked and or adjusted FONLY" with a STANDARD REFERENCE CARTRIDGE. (RLO1K-RF OR RLO2K-RF)
- o The "normal" setup and alignment/check procedures may be used. These are available using any of the following documents:
 - EK-RL012-PG-003 RL01/02 Pocket Service Guide
 - EK-RLTER-PS-002 RL01/02 Pocket Service Guide

4.0 CARTRIDGE CHECK

- o These guidelines should be followed when checking normal cartridges (RLO1K-DC, RLO1K-EF, RLO2K-DC, or RLO2K-EF) in drives that have been pre-aligned with a Standard Reference Cartridge.
- o Perform all Drive alignments/checks with a STANDARD REFERENCE CARTRIDGE (RLO1K-RF or RLO2K-RF) before checking other cartridges in the drive.

4.1 Cartridge Check - Servo Amplitude

- The amplitude of the S1 servo burst should be no less than 500mv on either head of any cylinder. (typically checked on the inner cylinder)
- The amplitude of the S1 servo burst should be no greater than 2.25v on either head of any cylinder. (typically checked at cylinder 0)
- If steps 1 and 2 above cannot be achieved, the cartridge should be rejected.

4.2 Cartridge Check - Sector-to-S1 Time

- Sector-to-S1 time should be 15us +/- 3us on both heads on any cylinder. (typically checked at the inner & outer cylinders)
- 2. If sector jitter exists (see Fig. 4), the upper limit of sector jitter should not exceed 18us and the lower limit should not fall below 12 us.
- 3. If steps 1 & 2 above cannot be achieved, the cartridge should be rejected.

Appendix A

**** Head Selection Procedures ****

PDP-11 Based Systems

DLM Version 1 or 2

- Load DZRLCxx or CZRLIxx

- Run Head Alignment routine

- Use WRITE PROT switch

In = select head 1
Out = select head 0

DLM Version 3

- Repower up RL drive to clear internal drive command/status register(s). This will assure Head O is default selected.

- Jumper TP21 to TP22 to select head 1

- Remove jumper to select head 0

Note: If diagnostics are unavailable, use the toggle-in program listed in Appendix B.

PDP-8 Based Systems

DLM Version 1 or 2

- Load AJRLBxx or AJRLHxx

- Run Head Alignment routine

- Use WRITE PROT switch

In = select head 1
Out = select head 0

DLM Version 3

- Repower up RL drive to clear internal drive command/status register(s). This will assure Head O is default selected.

- Jumper TP21 to TP22 to select head 1

- Remove jumper to select head 0

Note: If diagnostics are unavailable, use the toggle-in program listed in Appendix C.

Appendix B

**** Toggle-in Program ****

HEAD SELECTION FOR RL11/RLV11

1000 1002	012700 174400 012701	Housekeeping
1004 1006	174404	
1010	105710	Wait
1012	100376	
1014	012711	Get Status Command
1016	000013	
1020	012710	
1022	000004	· ·
1024	105710	Wait
1026	100376	Status Word
1030	013702	Status word
1032 '	174406 006302	
1034 1036	010203	
1040	006303	
1042	105702	Check HS Bit
1044	100405	
1046	005703	Check WL Bit
1050	100357	Equal, Loop
1052	012711	Set HS Bit
1054	000021	
1056	000404	Go to Seek Command
1060	005703	Check WL
1062	100752	Equal, Loop Reset HS Bit
1064	012711 000001	Reset no bit
1066 1070	012710	Seek Command
1070	000006	Doon Johnana
1074	000745	Loop
. • .		•

Appendix C

**** Toggle-in Program ****

HEAD SELECTION FOR RL8A

200 201	6600 1234	Clear controller
202		Get Status Command
		Wait
	5203	
		First Word of Status
206		
_		Check HS Bit
210		HS=1, Go to 217
210	6615	2nd word of Status
212		Zild Word of Dodods
		Check WL Bit
		HS=WL, Go to 201
214		115-HL, GO 00 201
215 216		
	6615	2nd Word of Status
· · ·		Zild Word of Budbus
220	0233	Check WL
221		HS=WL, Go to 201
	5201	ns=wl, Go to 201
•	7300	U. to Command Post A
224	6603	Hs to Command Reg A
225		G at Gammand to Command Por B
226	6604	Seek Command to Command Reg B
227	6601	Wait
230	5227	-
_		Loop to 201
232	0100	Constant
233	0040	Constant
234	1002	•

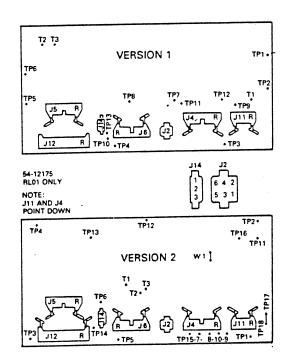
Appendix D

**** Service Jumpers for DLM (Drive Logic Module) ****

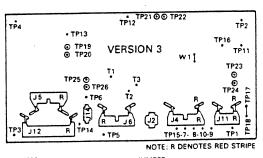
Version	Defeat Cover Switch	Defeat Filtered POS SIG	Defeat SK TO	Select Head 1
1	E33-3 to E33-7	TP8 to TP4	E17-6 to E17-7	See table 1
2	E54-12 to E54-7	TP6 to	E10-7 to E10-8	See table 1
3	TP19 to TP20	TP6 to ,	TP23 to	TP21 to TP22

Note:

Version 1 DLM = p/n 54-12175 (RL01 only) Version 2 DLM = p/n 54-13531 (obsolete) Version 3 DLM = p/n 54-14025 (RL01 or RL02)



54-13531 RL02 OR RL01 W1 IN FOR RL01 W1 OUT FOR RL02 NOTE: J4 AND J11 POINT UP NO TP19 THRU 26



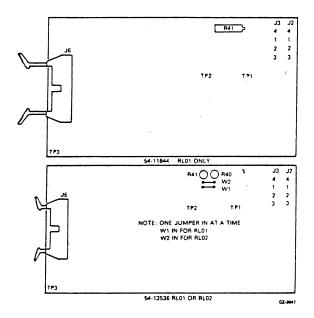
54-14025 RL02 OR RL01 W1 IN FOR RL01 W1 OUT FOR RL02 NOTE:

NOTE: J4 AND J11 POINT UI HAS TP19 THRU 26 JUMPER
TEST LUGS EFFECT
19-20 DEFEAT COVER CLOSED
21-22 SELECT HEAD 1
23-24 DISABLE SKTO

(THESE TEST LUGS ARE CIRCLED)

Appendix E

**** READ/WRITE MODULE LAYOUT ****



Notes: (for 54-13536)

- o W1 "in" selects R41 (normally for adjusting RL01)
- o W2 "in" selects R40 (normally for adjusting RL02)
- o If you are adjusting R40 or R42 on the 54-13536 and the potentiometer should happen to break, merely "exchange" the W1/W2 jumpers and use the other potentiometer for that drive.

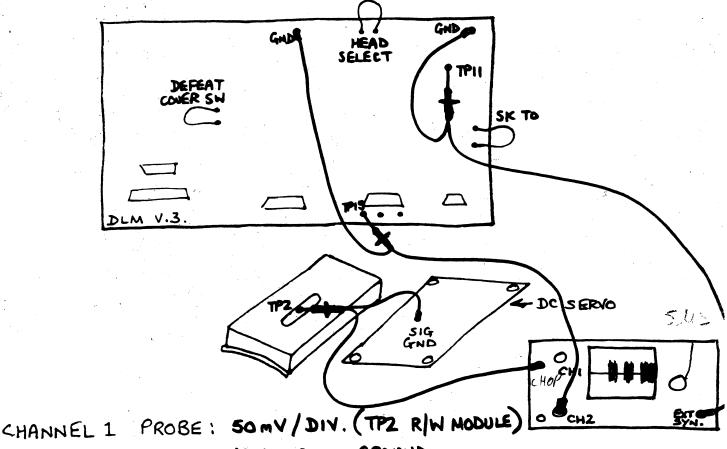
(both potentiometers are the same; W1/W2 merely determine which potentiometer is electrically inserted)

READINGS AFTER SETUP

VERIFICATION READINGS (NIA FIRST DRIVE)

DRIVE	SH			CARTRI	45 AN-			1	A.(66
O.D. CYLINDER OOD			. O.D. CYLINDER OOO			O.D. CYLINDER OBO					
			TOD BOTTOM		11 101						
SI AMP	SECTOR	SI AMP	SECTOR	SI AMP	SECTOR	SI AMP	SECTOR	SI AMP	SECTOR	SI AMP	FIN
-	TIME		1,17,1							1	
	0.77	WEB &			.D. CYLI	NDER 5	11	7	.D. CYLI	WDER 5	11
T.D. CYLINDER 511				20	BOT	MOT	TOP BOTTOM				
	ror	100	65(708)	CI OMP	SECTOR	ST AMP	SECTOR	SI AMP	SECTOR	SI AMP	SEC
SI AM	SECIOR	ZZ HIIIP	TIME	32	SECTOR		TIME		TIME		
						<u></u>		<u> </u>	<u> </u>		L
	3/N			PARTE	IDLE SN	-		_			
DRIVE	31N 0.D. CYL			CARIC	5 600	117E0 0	00	· · · · · · · · · · · · · · · · · · ·	D. CYLI	INDER O	00
1				., 6	OP	NVER D	T000	-	'0 P	Вот	TOM
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						ļ		f 1	1	1	f
ļ	I.D. CYL	WDER 5	11		.D. CYL				E.D. CYL		
		867	7000	7	OP	BOT	Tom		ro.P		
SI AM	P SECTOR TIME	ST AMP	SECTOR	SI AMP	SECTOR	ST AMP	SECTOR	SI AM	SECTOR	SI AMP	SE
:	TIME		TIME		LIME						
DRIVE	. S/N	INDER C	000	CART	RIDGE FI	NOER C	00	- 	o.D. CYL		
	= 5 0	B 0	MOT	TOP BOTTOM			TOP BOTTOM				
SI AME	SECTOR	SE AMP	SECTOR	SI AMP	SECTOR	SI AMP	SECTOR	SI AMP	SECTOR	SI AMP	SEC
	1.00							11	1	l .	İ
1	I.D. CYLINDER 511			I.D. CYLINDER 511			T.D. CYLINDER 511				
!	TOP	Bo.		H	rop		TOM				
SI AM	P SECTOR	SI AMP	SECTOR	SI AM	SECTOR	SI AMP	TIME	S1 AM	SECTOR	27 11111	7
	·]			<u> </u>
	1.1			. 0 1 07	EIDGE SI	J-		_			
DRIV	E 5/N							7	O.D. CYA	INDER	200
TOP BOTTOM			TOP BOTTOM			TOP BOTTON					
	TOP PI SECTOR			11			SECTO	SI AMP	SECTOR	SI AMP	SE
SI AM	TIME	32 71111	TIME	-	TIME	-	TIME	1	1		T
	I.D. CY	TODER 4	<u> </u>	-] I.d. Cyl	INDER :	511	┨╟───	1.D. CY1	INDER 3	511
	TOP		110W	11	TOP		TTOM	11	TOP	80.	TTON
SI AM		SI AMP		11	P SECTOR	SI AMP	SECTO	R SI AM	P SECTOR	SE AMP	SE
51 .AM	TIME		TIME		TIME	-	TIME	11	LINE		1
1	1	1	1	11		I	1	11	1 .		

ALINEMENT ON RLOQ USING VERSION 3 DLM



GROUND! ANY SIGNAL GROUND

PROBE: 2V/DIV. (TPIS) CHANNEL 2

GROUND! ANY SIGNAL GROUND

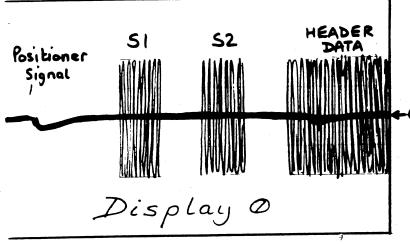
PROBE : (TPII) EXTERNAL TRICGER (AC COOPLING) . EXTERNAL

GROUND: SIGNAL GROUND DC SERVO MODULE SYNC.

- 1) Install The bottom head (HEAD 1) and before tightening slide head off the end stop by approximately 1 mm.
- 2) Install the top head (HEAD 0) and tighten only finger tig at this time
- 3) Load BLUE REFERENCE PACK', Link head select terminal with a jumper this will select the boltom head. Spin the drive up and the heads will load on to the pack with

the bottom head sitting directly over track o

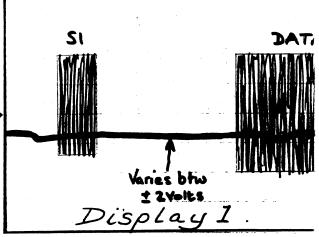
- 4) Disconnect the RED wire from the DC servo module to the Positioner (this will allow the heads to move freely over the pack, so be careful not to move the head off track o)
- 5) Remove the head select jumper, The oscilloscope display will show where head or is sitting. Adjust the top head outwards until the display matches that of the original display for head 1.



Head directly over track 'n'

Positioner Signal

Outer Golard band: +8 V.
Inner Golard band: -8 V.
Before track: -2 V rising.
After track: higher than 0 Volts.



when selecting head of after head 1 directly over track of, this type condisples should be seen.

Adjust top head outward until it is the same as display 0.

Be careful to make sure the top head is over track ϕ , its easy to go to far and line it up over the wrong track.

